Module Guide
Mechatronic and Cyber-Physical Systems

Faculty Applied Natural Sciences and Industrial Engineering
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MMC-01 Cyber-Physical Systems

Module code	MMC-01
Module coordination	Prof. Dr. Matthias Górka
Course number and name	MMC1001 Cyber-Physical Systems
Lecturer	Prof. Dr. Matthias Górka
Semester	1
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	6
ECTS	5
Workload	Time of attendance: 90 hours self-study: 60 hours Total: 150 hours
Type of Examination	written ex. 90 min.
Duration of Examination	90 min.
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

After finishing the module **"Cyber-Physical Systems" ,** the students have reached the following targets:

The participants in the module learn the principles of system development. The foundations are laid to identify customer requirements and convert them into technical requirements. Considering possible risks is also part of system development.

Professional competence:

- Capture and update requirements [4 - In-depth knowledge]
- Know and apply the product life cycle [4 - In-depth knowledge]

- Create, maintain and derive measures from D-FMEA [4 - In-depth knowledge]
- Consider safety aspects while design process [2 - basic knowledge]
- Designing systems [5 - Expert knowledge]

Methodological competence:

- Methods for requirements management, FMEA and idea generation.

Personal competence:

- Dealing with complex systems in volatile environments.

Social competence:

- Collaboration in interdisciplinary teams to create optimal systems.

Applicability in this and other Programs

The module provides the necessary theoretical background and transfer possibility for the design of a complete systems and the respective system parts. This includes their interfaces in the domain of mechanics, electric, electronic and computer science. The learned approaches can be used for the case studies and structured working on the master thesis.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering or bachelor's degree in industrial engineering, technical physics or computer engineering.

other requirements:

- Basic mathematics
- Basic presentation skills

Learning Content

- Requirements management
- Change management
- Product creation process
- Risk management and D-FMEA (design / product)
- Idea generation

Teaching Methods

- Seminar-like teaching with joint exercises as well as presentations to deepen the knowledge achieved through application
- i-Learn (online learning platform)
- Script

MMC-02 Advanced Robotics

Module code	MMC-02
Module coordination	Ginu Alunkal
Course number and name	MMC1002 Advanced Robotics
Lecturer	Ginu Alunkal
Semester	1
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	written ex. 90 min.
Duration of Examination	90 min.
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

This course covers advanced topics in robotics, focusing on the design, control, and application of robotic systems. The course integrates concepts from kinematics, dynamics, control theory, machine learning, and AI to address challenges in autonomous robotics. Students will work on practical projects involving simulation and real-world robotic systems.

Within the course **Advance robotics** , the following competences are to be taught:

1. Professional Competence

Students will:

- Master advanced robotic systems : Understand and apply the principles of kinematics, dynamics, and control in robotic manipulators and mobile robots.
- Design and implement robotic systems : Utilize industry-standard tools and software for robot modeling, control, and simulation, enabling the creation of sophisticated and functional robotic systems.
- Apply artificial intelligence in robotics : Use machine learning and AI techniques to enhance robot autonomy, perception, and decision-making, particularly in real-world, dynamic environments.

2. Methodological Competence

Students will:

- Develop problem-solving skills : Formulate and solve complex problems in robot motion planning, control, and sensor integration using analytical, numerical, and experimental methods.
- Employ advanced algorithms : Implement state-of-the-art algorithms for motion planning (e.g., A*, RRT), localization (e.g., Kalman filters, SLAM), and sensor fusion, adapting these to specific robotic tasks and challenges.
- Design and conduct experiments : Apply research methodologies to design, test, and validate robotic systems, ensuring robust performance and reliability through iterative development and rigorous experimentation.

3. Personal Competence

Students will:

- Enhance critical thinking and adaptability : Analyze, interpret, and critique advanced robotics literature and technologies, staying adaptive to evolving innovations and interdisciplinary approaches in the field.
- Demonstrate self-directed learning : Take initiative in mastering new robotic technologies and programming languages, independently seeking out resources, tutorials, and research materials to deepen their understanding.
- Develop project management skills : Plan, execute, and manage complex robotics projects from conception through implementation, while demonstrating time management and resource allocation skills.

4. Social Competence

Students will:

- Work collaboratively in teams : Engage in group projects requiring close cooperation, interdisciplinary communication, and problem-solving, fostering an environment of collaboration across technical and non-technical domains.
- Communicate effectively : Present complex technical information clearly and concisely, both orally and in written form, to peers, supervisors, and stakeholders in the robotics field.

- Understand ethical and societal impacts : Reflect on the ethical, societal, and economic implications of advanced robotics, including the impact on job markets, privacy, safety, and human-robot interaction, and contribute to discussions around responsible robotics development.

Applicability in this and other Programs

The module provides the necessary theoretical knowledge and transfer possibility for the application of autonomous system to provide irrespectively of the mobility platform for different application scenarios. Interfaces to mechatronics, control engineering, electrical engineering and computer science result.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering, industrial engineering, technical physics or computer science.

Basic knowledge in Matlab and Python programming is expected.

Also knowledge of linear algebra and calculus are expected.

Learning Content

Within the framework of the module " **Advanced Robotics** ", students deal with in-depth contents of manipulators, mobile and collaborative robotics. It will help students to understand the kinematics and dynamics of robots. 3D obstacle / object recognition, localization and map generation, as well as navigation and route planning play a decisive role. Cognitive systems, machine learning and artificial intelligence are also addressed.

Teaching Methods

Seminaristic teaching with joint exercises to deepen the theory learned through application

Recommended Literature

- Siciliano B., Khatib O.: Handbook of Robotics. Springer.
- Corke P.: Robotics, Vision and Control. Springer.
- Craig J. J.: Introduction to Robotics. Pearson Education.
- Spong M. W.: Robot Modeling and Control. Wiley.
- Siegert H. J., Bocionek S.: Robotik: Programmierung intelligenter Roboter. Springer.
- Brillowski Klaus: Einführung in die Robotik - Auslegung und Steuerung serieller Roboter. Shaker-Verlag.

MMC-03 Autonomous Systems

Module code	MMC-03
Module coordination	Prof. Dr. Dmitrii Dobriborsci
Course number and name	MMC1003 Autonomous Systems
Lecturers	Prof. Dr. Dmitrii Dobriborsci N.N.
Semester	1
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	written ex. 90 min.
Duration of Examination	90 min.
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The contents of the module **Autonomous Systems** enable students to apply advanced knowledge in robotics focusing on the basics of robotics. Networking with autonomous systems supports the application-oriented teaching of the methodology and professional competence of robotics.

After completing the Autonomous Systems module, students will be able to

- Develop application-oriented solutions from the acquired methods for autonomous systems with regard to localization, navigation, route planning, obstacle recognition and tracking;

- Analyze and apply robotic methods in a targeted manner;
- Using the generated methods in simulation models.

Within the module **Autonomous Systems** , the following competences are to be taught:

Professional competence:

- Understanding and applying methods of autonomous systems
- Modelling of environmental conditions and vehicle relations
- Applying the methods for the localization of mobile robots
- Application of methods for obstacle recognition and path planning
- Analysis of control loops for autonomous systems
- Understanding and applying Denavit-Hartenberg Relationships
- Understanding and applying forward and inverse kinematics
- Application of robot simulations and programming of robots

Methodological competence:

- Application of robot programming
- Verification (evaluation) of robot motions
- Application of localization, navigation, path planning, and obstacle detection of autonomous systems
- Application of calculated robot relations in suitable simulation systems

Personal competence:

- Solution of complex robotics topics and their application as autonomous systems

Social competence:

- Students are able to look at autonomous systems and to deepen and use the competences acquired in the module in a prepared way.

Applicability in this and other Programs

The module provides the necessary theoretical knowledge and transfer possibility for the application of autonomous system to provide irrespectively of the mobility platform for different application scenarios. Interfaces to mechatronics, control engineering, electrical engineering and computer science result.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering, industrial engineering, technical physics or computer science.

Basic knowledge and experience in Python are necessary for the second part of the lab-sessions. However, students with prior experience in Matlab, R or other programming languages may be acceptable given an introductory Python tutorial outside of the module.

Also knowledge of linear algebra and calculus are expected.

Learning Content

Within the framework of the module " **Autonomous Systems** ", students deal with in-depth contents of mobile and collaborative robotics. 3D obstacle / object recognition, localization and map generation, as well as navigation and route planning play a decisive role. Cognitive systems, machine learning and artificial intelligence are also addressed.

Teaching Methods

Seminaristic teaching with joint exercises to deepen the theory learned through application

Recommended Literature

- Siciliano B., Khatib O.: Handbook of Robotics. Springer.
- Corke P.: Robotics, Vision and Control. Springer.
- Craig J. J.: Introduction to Robotics. Pearson Education.
- Spong M. W.: Robot Modeling and Control. Wiley.
- Siegert H. J., Bocionek S.: Robotik: Programmierung intelligenter Roboter. Springer.
- Brillowski Klaus: Einführung in die Robotik - Auslegung und Steuerung serieller Roboter. Shaker-Verlag.

MMC-04 Case Study Cooperative and Autonomous Systems

Module code	MMC-04
Module coordination	Ginu Alunkal
Course number and name	MMC1004 Case Study Cooperative and Autonomous Systems
Lecturers	Ginu Alunkal Christy Paul
Semester	1
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	Portfolio
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The module " **Case Study Cooperative and Autonomous Systems** " enables students to apply the knowledge acquired within the module " **Autonomous Systems** ", to deepen it independently and to work on and analyse subject-relevant application examples in a team.

Professional competence:

- Understanding and applying methods of autonomous systems
- Modelling of environmental conditions and vehicle relations

- Applying the methods for the localization of vehicles in space
- Application of methods for obstacle recognition and route planning
- Analysis of control loops for autonomous systems
- Understanding and Applying Denavit-Hartenberg Relationships
- Understanding and applying forward and inverse kinematics
- Application of robot simulations and programming of robots
- Understanding and applying the functions for joint collaboration between robots and humans.
- Understanding and applying methods of machine learning, in particular artificial intelligence
- Understanding different approaches to building assembly lines

Methodological competence:

- Application of robot programming
- Verification (evaluation) of robot movements
- Application of localization, navigation, route planning, and obstacle detection of autonomous systems
- Application of calculated robot relations in suitable simulation systems

Personal competence:

The "Case Study Cooperative and Autonomous Systems" teaches students how to solve complex robotic problems and how to use them as autonomous systems in groups with distributed tasks. The students learn how to analyze, apply and evaluate a task in relation to autonomous systems.

Social competence:

Students are able to view autonomous systems on the basis of case studies and to deepen and use their competences acquired from the module in group work.

Applicability in this and other Programs

Interfaces to mechatronics, control engineering, electrical engineering and computer science.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering, industrial engineering, technical physics or computer science

Learning Content

On the basis of a selected application example, students are supposed to carry out independ literature research, if necessary independent small subtasks,etc. and work on the topic themselves by means of literature research.

Sample Autonomous Systems

- Characteristics of the required control loops of networked systems
- Sensors / actuators for vehicle control
- Localization and Mapping
- Route planning, tracking and obstacle detection
- ...

The case studies are examined as so-called examination papers, i.e. no classical examination.

Teaching Methods

Guided processing of seminar topics in study groups. Accompanying events / presentations depending on the selected topic area.

Remarks

The students learn to analyze and apply theoretical knowledge about the topics of the case study independently. This intensifies the transfer of knowledge into practice and the targeted deepening of the acquired technical and methodological competencies by recognizing contexts and evaluating them.

Recommended Literature

- Siciliano B., Khatib O.: Handbook of Robotics. Springer.
- Corke P.: Robotics, Vision and Control. Springer.
- Craig J. J.: Introduction to Robotics. Pearson Education.
- Spong M. W.: Robot Modeling and Control. Wiley.
- Siegert H. J., Bocionek S.: Robotik: Programmierung intelligenter Roboter. Springer.
- Brillowski Klaus: Einführung in die Robotik - Auslegung und Steuerung serieller Roboter. Shaker-Verlag.

MMC-05 Advanced Modelling and Simulation

Module code	MMC-05
Module coordination	Prof. Dr. Peter Firsching
Course number and name	MMC1005 Advanced Modelling and Simulation
Lecturer	Prof. Dr. Peter Firsching
Semester	1
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	Portfolio
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The digital transformation of industrial processes relies heavily on the availability of suitable models. These models are used in virtual product development, in the digitalisation of plant operation and maintenance, but also in the virtual description of processes, e.g. in control systems or material flows. The focus of this course is therefore on the modelling of technical systems as a basis for system simulation.

The content of the "Advanced Modelling and Simulation" module enables students to select and design models of technical systems and processes for different applications. The technical and methodological skills described below are taught for this purpose.

After completing the Advanced Modelling and Simulation module, students will be able to

- model technical systems using simple balancing approaches

- select the required methods from the methods learned for experimental modelling and incorporate them into a modelling process.
- apply methods for the experimental generation of models of dynamic systems, state machines and machine learning and analyse the model results in a targeted manner,
- assign and use the generated models to simulation tools in a suitable manner.

In the module Advanced Modelling and Simulation, the following competences are to be taught:

Professional competence:

- Understanding and applying methods of experimental modelling of dynamic systems
- Consolidation (synthesis) of the model-building methods to complex overall models
- Understanding and applying methods of machine learning, especially artificial neural networks in the modelling process
- Understanding different approaches to the design of simulation systems

Methodological competence:

- Application of state machines for the modelling of technical systems
- Verification (evaluation) of modelling results
- Application of generated models in suitable simulation systems
- Assessment of the suitability of models for the phases of a product development process.

Personal competence:

- Solution of complex modelling and simulation tasks

Social competence:

- The students are able to look at the problems from different perspectives and to use their competences acquired in the module situation appropriately in individual and group discussions.

Applicability in this and other Programs

The module provides the necessary theoretical knowledge and the transfer capability to provide technical systems in the form of suitable models for different simulation scenarios. This creates interfaces to courses of study, such as mechanical engineering, mechatronics and computer engineering.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering or bachelor's degree in industrial engineering, technical physics or computer engineering.

Learning Content

I Mathematical Models of Physical Systems

- Differential Equations of Physical Systems
- Linear Approximation of Non Linear System Equations
- Signal Flow Charts
- State Space Models of Linear Systems
- Discrete Time Systems

II System Identification by Parameter Identification

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- Theoretical and Experimental System Analysis
- Parameter Identification in Time Domain
- Parameters of nth Order Time Delay Systems
- Parameter Identification in Frequency Domain

III Parameter Estimation

- Principles of Parameter Estimation
- The Least Squares Method
- The Steepest Descend Method
- Parameter Estimation of dynamic Systems
- System Models based on Neural Networks

IV Finite State Machines

- Basics of Finite State Machines
- Applications in Industrial Control

V Simulation Systems

- The History of Simulation: Analogue Computing
- Simulation Scenarios / Process Modells - Block Oriented vs. Object Oriented Simulation
- Simulation Systems Overview

Teaching Methods

Seminaristic teaching with group work and joint exercises as well as presentations to deepen the knowledge achieved through application

Remarks

It is particularly important that students apply the theoretical knowledge acquired in this module comprehensively to the topics of the "Mechatronic System Simulation" case study module. This intensifies the transfer of knowledge into practice and the targeted deepening of the acquired technical and methodological competencies through the recognition of contexts and their evaluation.

Recommended Literature

Robert L. Woods, Kent L. Lawrence: Modeling and Simulation of Dynamic Systems. Prentice Hall, 1997

Isermann R.: Identification of dynamic systems. Springer-Verlag, 2011.

Ljung L., Glad T.: Modeling of dynamic systems. Prentice Hall, 1994

Dorf R. C., Bishop R. K.: Modern Control Systems. Pearson Educational International, 2017.

David Kriesel: A Brief Introduction to Neural Networks. eBook, http://www.dkriesel.com/en/science/neural_networks , 2005.

Litz L.: Grundlagen der Automatisierungstechnik. Oldenbourg-Verlag, 2013.

Wernstedt J.: Experimentelle Prozeßanalyse. Oldenbourg-Verlag, 1989.

MMC-06 Case Study Mechatronic System Simulation

Module code	MMC-06
Module coordination	Dr. Sunil Survaiya
Course number and name	MMC1006 Case Study Mechatronic System Simulation
Lecturers	Christy Paul Dr. Sunil Survaiya
Semester	1
Duration of the module	1 semester
Module frequency	
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	Portfolio
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The " **Case Study: Mechatronics System Simulation** " (CS-MSS) allows you to simulate the physical behavior and interactions of application system components such as sensors, actuators, motors, gears, and controllers. Simulating various situations and conditions, such as loads, disturbance, feedback, and noise, allows you to study, evaluate, and optimize multiple design options, identify and eliminate bottlenecks, and fine-tune your system parameters.

The CS-MSS program also teaches methodology and professional skills for developing parametric and non-parametric models, as well as creating process descriptions. It also encourages independent analysis, synthesis, and evaluation of modeling and simulation tasks within the team.

After completion of CS-MSS module, students will have the following competencies:

Professional competence:

- Understanding the concept of model simulation
- Understanding of the model-building blocks needed to solve complex problems
- Understanding different approaches to simulation systems development and integration

Methodological competence:

- Application of generated models in suitable simulation systems
- Assessment of the suitability of models for the phases of a product development process.
- Verification and optimization of modelling results

Personal competence:

- The CS-MSS teaches the students how to solve complex modeling and simulation tasks in teams with distributed task areas.
- The students learn how to analyze, synthesize, and evaluate a task in relation to mechatronic systems.

Social competence:

- Students are able to approach challenges from different perspectives and apply their module-specific competencies individually and in group.

Applicability in this and other Programs

Interfaces to study course, such as mechanical engineering, mechatronics and computer engineering.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering or bachelor's degree in industrial engineering, technical physics or computer engineering.

Learning Content

- A basic introduction to logical programming concepts using MATLAB.
- A basic introduction to passive and active electronic components
- A basic introduction to sensors and actuators
- A basic introduction to control systems.

It is necessary for the students to form groups of three to four, depending on the course participants. This offers a framework for group collaboration. The group can choose to propose a simulation project or choose a scientific research paper related to CS-MSS. The group assessment is conducted using the following criteria:

- Concept Presentation
- Status reviews (Presentation)
- Final project demonstration
- Final Presentation
- Report submission

NOTE: Depending on the faculty member, different criteria may apply.

Teaching Methods

- Guided processing of seminar topics in working groups.
- Accompanying events / presentations by external lecturers, depending on the selected topic area.

Remarks

Theoretical knowledge from the MCS-4 module "Advanced Modelling and Simulation" must be independently applied by the students to the case study subjects. By identifying contexts and evaluating them, this enhances the transfer of knowledge into practice and the targeted deepening of the technical and methodological competencies that have been acquired.

Recommended Literature

Robert L. Woods, Kent L. Lawrence: Modeling and Simulation of Dynamic Systems. Prentice Hall, 1997

Isermann R.: Identification of dynamic systems. Springer-Verlag, 2011.

Ljung L., Glad T.: Modeling of dynamic systems. Prentice Hall, 1994

Dorf R. C., Bishop R. K.: Modern Control Systems. Pearson Educational International, 2017.

David Kriesel: A Brief Introduction to Neural Networks. eBook, http://www.dkriesel.com/en/science/neural_networks , 2005.

Litz L.: Grundlagen der Automatisierungstechnik. Oldenbourg-Verlag, 2013.

Wernstedt J.: Experimentelle Prozeßanalyse. Oldenbourg-Verlag, 1989.

MMC-07 Human Machine Interfaces - VR/AR

Module code	MMC-07
Module coordination	Prof. Dr. Ralph Hensel-Unger
Course number and name	MMC2001 Human Machine Interfaces - VR/AR
Lecturers	Prof. Dr. Ralph Hensel-Unger Prof. Dr. Anton Schmailzl
Semester	2
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	written ex. 90 min.
Duration of Examination	90 min.
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The module imparts basic knowledge about the essential topics of the digital extension possibilities - the "Extended Reality" - of technically real solutions in the field of system engineering development. In the foreground are software applications for the realization of the HMI - Human Machine Interface - via different sensory perceptions and the technical concepts for the implementation of the corresponding content by controllers, such as an HMD - Head Mounted Display. In this context, the different digital extensions and definitions are discussed. Furthermore, the conceptual planning and implementation of VR/AR projects are covered in the byway of the lecture.

After completion of this module, the student has achieved the following learning objectives:

Professional competence:

- Virtual and Augmented Reality systems and applications;
- Applied technologies in the field of Virtual and Augmented Reality;
- Current topics of the first generation for Extended Reality applications;
- Students can design, criticize, and implement mobile human-machine interfaces that meet the guidelines for usability, user experience, and experience quality.
- Students understand the visual perception and haptics of people with regard to the development of efficient graphical user interfaces.
- Students can analyze a defined and realized topic in the AR or VR-project area;
- Role definition according to the domain hardware, software or system within a group;

Methodological competence:

- Understand, analyze and synthesize information about Extended Reality-system technologies;
- Communicate with vendors of AR and VR-system components, such as headsets;
- Discussion of important technical issues, such as controller, field of view and inside-outside tracking.
- Collection of initial experience in the design process, including background information such as passport law.
- Students are able to create personas, scribbles and wireframes.
- Students know how to implement their design with web technology, progressive web applications and native Android programming.

Personal competence:

- Construct simple AR/VR applications
- Acquisition and transfer of system terminology

Social competence:

- Presentation of individual technology solutions and limitations of announced AR/VR projects.

Applicability in this and other Programs

Human Machine Interfaces:

Generic and basic topics are included and represent use cases for all study programs of the Faculty of Applied Natural Sciences and Industrial Engineering;

VR/AR:

The module provides a basis for HMI modules in all study programs of the Faculty of Applied Natural Sciences and Industrial Engineering.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering or bachelor's degree in industrial engineering, technical physics or computer engineering.

Learning Content

Human Machine Interfaces:

Perception:

- The human eye
- Human visual perception
- Higher cognitive processes
- Gestalt Theory

Human-Machine interaction concepts:

- Cognitive background
- Utility, Usability, User Experience
- Quality of Experience

Designing for User Experience:

- 4 Steps of the design process
- Specific considerations for design on mobile devices
- Design principles for interactive Web applications using HTML, CSS, Javascript

Exercise on User Experience Design:

- Designing a sample application
- Refreshing HTML, CSS, Javascript
- Frameworks for Mobile Application Development
- Understanding Cordova and implementing the sample application

Native Application development with Android:

- Understanding the application life cycle
- Tools of Android development
- Guidelines for material design usage
- Implementing a sample application

VR/AR:

- History in context
- VR and AR Technology
- Used form factor in AR and VR
- Current state of the first generation AR and VR
- Current issues in AR and VR
- Consuming Content in AR and VR
- Projects` creation

Teaching Methods

Lectures / tutorials / home work / group activities
Whiteboard, visualizer online learning portal (iLearn).
The course uses a seminar style alternating between lectures and exercise phases.

Recommended Literature

Human Machine Interfaces:

- Bruce Goldstein, ?Sensation and Perception?, 10. Auflage, 2016, Cengage Learning, 10th edition, ISBN: 978-1305580299
- Jens Jacobsen, Lorena Meyer, ?Praxisbuch Usability und UX?, Rheinwerk Computing, ISBN: 978-8362-4423-7
- Jan Semler, ?App-Design?, Rheinwerk Design, 2016, ISBN: 978-3-8362-3453-5
- W3schools, Tutorials on HTML, CSS, Javascript, available online: https://www.w3schools.com
- Android, ?Up and Running with Material Design?, online: https://developer.android.com/design/index.html
- iOS, ?Human Interface Guidelines, iOS Design Themes?, online: https://developer.apple.com/ios/human-interface-guidelines/overview/themes/

VR/AR:

- Paul Mealy: Virtual & Augmented Reality for dummies; John Wiley;
- Gartner: Hype Cycle Report 2018
- German Patent Search: https://www.dpma.de
- European Patent Search: https://epo.org
- US-Search: http:// patft.uspto.gov

MMC-08 Case Study VR/AR in System Engineering

Module code	MMC-08
Module coordination	Prof. Dr. Ralph Hensel-Unger
Course number and name	MMC2002 Case Study VR/AR in System Engineering
Lecturers	Prof. Dr. Ralph Hensel-Unger Prof. Dr. Anton Schmailzl
Semester	2
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 120 hours Total: 180 hours
Type of Examination	Portfolio
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

In the **Case Study VR/AR in System Engineering** , the students will work on selected examples thematically a project team with differently defined roles and work packages. In a first review, the topic will be explained through research and existing solutions will be pointed out. The overall process of the machining process by way of a "value chain" is realized through research - synthesis - design - prototype and evaluation.

After completion of this module, the student has achieved the following learning objectives:

Professional competence:

- Virtual and Augmented Reality systems and applications

- Students can design, criticize, and implement mobile human-machine interfaces that meet the guidelines for usability, user experience, and experience quality.
- Students can analyze a defined and realized topic in the AR or VR-project area;
- Creation of a case study: final report of all group members with defined generation process;

Methodological competence:

- Understand, analyze and synthesize information about Extended Reality-system technologies;
- Students are able to create personas, scribbles and wireframes.
- Students know how to implement their design with web technology, progressive web applications and native Android programming.

Personal competence:

- Construct simple AR/VR applications
- Acquisition and transfer of system terminology
- The exercises will be carried out in small groups of 4 students each and a support and peer review process will be set up between the groups.

Social competence:

- Presentation of individual technology solutions and limitations of announced AR/VR projects.
- Improving team and communication skills, including fair and productive criticism of other groups' work.

Applicability in this and other Programs

Human Machine Interfaces - VR/AR

Generic and basic topics are included and represent use cases for all study programs of the Faculty of Applied Natural Sciences and Industrial Engineering. The module provides a basis for HMI modules in all study programs of the Faculty of Applied Natural Sciences and Industrial Engineering.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering or bachelor's degree in industrial engineering, technical physics or computer engineering.

Learning Content

- Project aquisition
- Role definition

- Preperation of summarized report
- Presentation

Teaching Methods

Case Study VR/AR in System Engineering:

- Self-study based on theme paper
- Project team work

Recommended Literature

- Paul Mealy: Virtual & Augmented Reality for dummies; John Wiley;

MMC-09 Technologies of Additive Manufacturing

Module code	MMC-09
Module coordination	Prof. Dr. Matthias Hien
Course number and name	MMC2003 Technologies of Additive Manufacturing
Lecturer	Prof. Dr. Matthias Hien
Semester	2
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	written ex. 90 min.
Duration of Examination	90 min.
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The module has the following learning objectives:

- The students understand the Additive Manufacturing (AM) production process in detail.
- They can name and transparently describe the common AM technologies.
- The students can explain the AM process chain.
- The students can describe the advantages and disadvantages of the AM-technology in detail.
- The students can calculate the major economical process key values of the AM-technology.

- The students know the keystones for a successful implementation of metal based AM-technologies.
- The students can apply the basic design rules for a metal based AM process.
- The students have an understanding of the future perspective of the AM-technology.

Applicability in this and other Programs

MMC-14: Master's Module

Continuing: PhD work or PhD studies

Entrance Requirements

Bachelor's degree according to examination study regulations.

Learning Content

Additive Manufacturing in accordance with 3D-print based on a concatenation of innovative technical sub-disciplines. These are illustrated along the whole manufacturing process and discussed in appropriate professional manner.

- Acquisition and processing of 3D-data
- Detailed procedure of selected additive production processes
- Production-ready design (selection of forms and structures, support structures, bionic approaches)
- Materials (plastics, metals, binder, classification, characteristics)
- Production process

Additive respectively with 3D-print manufactured products do not only replace conventional products. The special characteristics of the production process enable new and process specific product features. Thereof again specific business models or process subsequences can be revealed, which are only applicable in additive manufacturing. The following topics outline these specific processes:

- Additive Manufacturing Production Process: Introduction, Classification and Definition
- Characteristics of AM Technology
- Technology Overview and Application Examples
- Economic Significance of Additive Manufacturing Technology
- Economic Calculation of the Additive Manufacturing Process
- Motivation for Additive Manufacturing beyond Economic Benefits
- Metal Additive Manufacturing Getting Started
- Design for Metal Additive Manufacturing

- Future Perspective of Additive Manufacturing

Contributions from experts based in the industry can deepen the understanding of specific topics.

Teaching Methods

Type of teaching: Seminaristic instruction / exercise, home exercises

Media form: presentation with projector, blackboard, videos, exhibits, additional documents about iLearn drive

Remarks

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Recommended Literature

Additive Manufacturing Technologies
Gibson, Ian; 2014; (459 pages)
Springer publishing house; 2014

Additive manufacturing: 3D printing for prototyping and manufacturing
Gebhardt, Andreas; (611 pages)
Carl Hanser publishing house; 2016

Detailed script and selected scientific publications about ilearn platform

MMC-10 AM Production Processes

Module code	MMC-10
Module coordination	Prof. Dr. Stefan Scherbarth
Course number and name	MMC2004 AM Production Processes
Lecturers	Prof. Dr. Matthias Hien Prof. Dr. Stefan Scherbarth
Semester	2
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	written ex. 90 min.
Duration of Examination	90 min.
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The module has the following learning objectives:

- The students understand the Additive Manufacturing (AM) production process in detail.
- They can name and transparently describe the common AM technologies.
- The students can explain the AM process chain.
- The students can describe the advantages and disadvantages of the AM-technology in detail.
- The students can calculate the major economical process key values of the AM-technology.

- The students know the keystones for a successful implementation of metal based AM-technologies.
- The students can apply the basic design rules for a metal based AM process.
- The students have an understanding of the future perspective of the AM-technology.

Applicability in this and other Programs

MMC-14: Master's Module

Continuing: PhD work or PhD studies

Entrance Requirements

Bachelor's degree according to examination study regulations.

Learning Content

Additive Manufacturing in accordance with 3D-print based on a concatenation of innovative technical sub-disciplines. These are illustrated along the whole manufacturing process and discussed in appropriate professional manner.

- Acquisition and processing of 3D-data
- Detailed procedure of selected additive production processes
- Production-ready design (selection of forms and structures, support structures, bionic approaches)
- Materials (plastics, metals, binder, classification, characteristics)
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Additive respectively with 3D-print manufactured products do not only replace conventional products. The special characteristics of the production process enable new and process specific product features. Thereof again specific business models or process subsequences can be revealed, which are only applicable in additive manufacturing. The following topics outline these specific processes:

- Additive Manufacturing Production Process: Introduction, Classification and Definition
- Characteristics of AM Technology
- Technology Overview and Application Examples
- Economic Significance of Additive Manufacturing Technology
- Economic Calculation of the Additive Manufacturing Process
- Motivation for Additive Manufacturing beyond Economic Benefits
- Metal Additive Manufacturing Getting Started
- Design for Metal Additive Manufacturing

- Future Perspective of Additive Manufacturing

Contributions from experts based in the industry can deepen the understanding of specific topics.

Teaching Methods

Type of teaching: Seminaristic instruction / exercise, home exercises

Media form: presentation with projector, blackboard, videos, exhibits, additional documents about iLearn drive

Remarks

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Recommended Literature

Additive Manufacturing Technologies
Gibson, Ian; 2014; (459 pages)
Springer publishing house; 2014

Additive manufacturing: 3D printing for prototyping and manufacturing
Gebhardt, Andreas; (611 pages)
Carl Hanser publishing house; 2016

Detailed script and selected scientific publications about ilearn platform

MMC-11 Case Study Cyber-Physical Production Systems Using AM

Module code	MMC-11
Module coordination	Prof. Dr. Matthias Hien
Course number and name	MMC2005 Case Study Cyber-Physical Production Systems Using AM
Lecturer	Prof. Dr. Matthias Hien
Semester	2
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	Portfolio
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

The module has the following learning objectives:

- The students understand the Additive Manufacturing (AM) production process in detail.
- They can name and transparently describe the common AM technologies.
- The students can explain the AM process chain.
- The students can describe the advantages and disadvantages of the AM-technology in detail.
- The students can calculate the major economical process key values of the AM-technology.

- The students know the keystones for a successful implementation of metal based AM-technologies.
- The students can apply the basic design rules for a metal based AM process.
- The students have an understanding of the future perspective of the AM-technology.

Applicability in this and other Programs

MMC-14: Master's Module

Continuing: PhD work or PhD studies

Entrance Requirements

Bachelor's degree according to examination study regulations.

Learning Content

Topics which can be covered within the framework of the case study:

- development supporting use
- decentralized spare part production
- food-printing
- medical technological application
- bioprint technology
- reverse engineering
- tooling

Case studies are so-called "Prüfungsstudienarbeiten" (student research projects), there will be no classic exam at the end of the semester.

Teaching Methods

group work, ilearn, exercises, presentation

Recommended Literature

Additive Manufacturing Technologies
Gibson, Ian; 2014; (459 pages)
Springer publishing house; 2014

Additive manufacturing: 3D printing for prototyping and manufacturing
Gebhardt, Andreas; (611 pages)
Carl Hanser publishing house; 2016

Detailed script and selected scientific publications about ilearn platform

MMC-12 Functional Safety - Principles and Design

Module code	MMC-12
Module coordination	Prof. Dr. Roland Platz
Course number and name	MMC2006 Functional Safety - Principles and Design
Lecturers	N.N. Prof. Dr. Roland Platz Norbert Sosnowsky
Semester	2
Duration of the module	1 semester
Module frequency	annually
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	4
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	written ex. 90 min.
Duration of Examination	90 min.
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	English

Module Objective

Within the module ' **Functional Safety - Principles and Design** ', students learn to follow developments in the areas of operational safety and occupational safety over the course of time. Functional safety is classified in the comprehensive field of process and machine safety. The students work out general objectives and influencing factors for the application of safety technology.

Students learn about European treaties as the basis for directives, harmonized standards and occupational safety. In this context, the European legislative procedure, with regard to the development of technical guidelines and standards, will be presented.
Within the framework of this module, the students will become familiar with relevant technical guidelines with regard to the development of safe machines and processes.

A detailed examination of the Machinery Directive provides students with the necessary basic knowledge. Students learn about current developments in existing safety standards and guidelines. This results from the strong overlapping of IT security and machine security in the future in terms of industry 4.0, with the use of cyber-physical systems.

The students can understand the processes involved in the development of standards. They recognize the importance of harmonizing standards that should be applied with regard to the development of processes/machines in order to achieve conformity with European safety directives.

The learning section also introduces national and international organizations for standardization. In the course of a standards research, relevant standards from the areas of safety and functional safety are identified.

The students learn the meaning and the procedure for a CE-certification. In the context of the explanation of the CE certification process, the detailed consideration of risk analysis and risk reduction takes place on the basis of relevant, international standards EN ISO 12100 and EN ISO13849 at selected study examples. In the course of this work, the use of special software for the systematic evaluation of safety functions will be presented.

The participants of the module gain an insight into the application of statistical methods in the fields of safety engineering and reliability analyses. An overview of relevant parameters and distribution functions is given by the analysis of exemplary data sets. The students work out general objectives and influencing factors in the application of safety engineering. Using an example project along ISO 26262, the students learn how to apply a product in consideration of the prescribed methods.

Within the framework of this module, students are introduced to relevant technical guidelines with regard to the development of safe products and their development processes and tools. Students learn about current developments in existing safety standards and guidelines. This results from the future strong overlap of IT security and product security in the course of industry 4.0, when using cyber-physical systems. The students learn the meaning and the procedure with a development tool certification.

The participants of the module gain an insight into the application of methods in the areas of security technology. An overview of relevant parameters and distribution functions is given by analyzing exemplary data sets.

After completing this module, students have achieved the following learning objectives:

Professional competence:

- The students have built up a sound basic knowledge in the field of safety engineering, in particular functional safety.

- The students know and apply the legal framework and processes with regard to the creation of technical guidelines and the resulting harmonized standards, as well as the implementation of the European requirements at national level.
- The students are familiar with the current European directives (Machinery Directive, Low Voltage Directive and Electromagnetic Compatibility Directive) and understand their influence on development work and plant procurement.
- Students are familiar with the basic technical standards that must be taken into account when integrating safety functions. In this context, the EN ISO 12100 and EN ISO 13849 standards play a particularly important role in the module.
- The students are familiar with the technical process of CE-certification and understand the effects on the development process and machine procurement. They are aware of the legal obligations that apply in the course of CE-certification.
- The students know and understand the legal framework and processes related to the creation of technical products.
- The students are familiar with the basic technical standards that must be taken into account when integrating safety functions. In this context, the ISO 26262 standards play a particularly important role in the module.
- The students know the technical process of a safety-relevant development and understand the effects on the development process and the responsibility of customers and suppliers. They are aware of the legal obligations
- Students have a basic knowledge of statistical analysis of data sets in the field of safety engineering and reliability analysis.

Methodological competence:

- The students acquire the ability to conduct a targeted research of standards and guidelines.
- With their basic knowledge of directives, standardization and CE-certification, students are able to carry out a basic risk analysis in accordance with the EN ISO 12100 standard. In addition, the students have the methodological competence to design safety-related parts of control systems (SRP/CS) according to the required performance level PLr using appropriate safety software (SISTEMA).
- With the technical basic knowledge about guidelines and standards it is possible for the students to implement the methodical competence of the safety-related parts of control systems.

Personal competence:

- The students acquire skills and strategies with which they can constantly update their knowledge with regard to safety technology in the rapid technological upheaval in the course of Industrialization 4.0.
- In the course of the module, students will be able to reflect on their responsibilities, which must be taken into account when designing new processes, machines or products with regard to safety aspects.

Social competence:

- Students acquire the ability to work together in mixed development teams, with special emphasis on clear communication and conflict management.

Applicability in this and other Programs

- Knowledge of standardization and standards research
- Statistical methods
- Methods for designing safe machines and processes

Entrance Requirements

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Learning Content

Functional Safety - Principles & Design

- Safety technology and occupational safety in the course of time
- Basics and terms of safety engineering
    - Distinction between system and functional safety
    - Goals and influencing factors in the development of safety concepts
- Legal framework in Europe with regard to safety technology
- Safety and health at work on the basis of European treaties
- Development of safety standards on the basis of European directives
- Future developments regarding the combination of IT security and functional security
- European directives for the development of safe machines
- Relevant Functional Safety Guidelines
- Machinery Directive 2006/42/EC
- Standards for safety technology
- Historical development in the field of standardization
- Definitions and terms from the field of standardization
- Significance, application and development of standards
- Harmonized standards
- International and national standard organizations

- Hierarchies and groupings of standards
- Presentation and comparison of standards in the field of functional safety.
- Practical approach to standards research. Exercises
- CE-certification
- CE-certification process
- Effects and influence of CE-certification on the development process and machine procurement
- Legal liabilities due to CE-certification and advantages of the CE-certification process at a glance
- Risk analysis according to the EN ISO 12100 standard using examples
- Risk reduction and design of safety functions in accordance with the EN ISO 13849 standard on the basis of examples
- Statistical methods in the field of safety engineering and reliability analysis
- Utilisation of a project example: Electrical steering without a redundant mechanical gear
- Functional Safety vocabulary
- Management of functional safety
    - Project independent safety management
    - Safety management during concept phase and development
    - Safety management activities after start of production
- Concept phase
    - Item definition
    - Initialisation of the safety life cycle
    - Safety integrity level analysis and risk assessment
    - Functional safety concept
- System product development
    - System development and integration
    - Product development hardware
    - Start of hardware development
    - Hardware safety requirements analysis
    - Hardware design
    - Quantitative requirements for random errors
    - Evaluation of random error effects on the safety goals
    - Hardware integration and test
    - Product development software
    - Start of software development
    - Software safety requirements specification
    - Software architecture and design
    - Software implementation
    - Software module test
    - Software integration and test
    - Software validation against the safety requirements

- Production and use
    - Production
    - Use, service and end of useful life
- Supporting processes
    - Interfaces
    - Specification of safety requirements
    - Configuration and change management
    - Verification
    - Documentation
    - Software tools qualification
    - Qualification of hardware components
    - Qualification of software components
- ASIL and SIL safety-oriented analysis
    - Decomposition and tailoring
    - Co-existence criteria
    - Error dependencies
    - Safety analysis
- Guideline support to use for ISO 262626 based on ISO/TS 16949 and IEC 61508.

Teaching Methods

The module provides a framework for self-organized learning to help students develop their professional and methodological skills.
In addition to theoretical inputs, interaction exercises and problem-solving tasks are used as central methods. Through guided work assignments, students are actively involved in the development of learning content. Practical exercises and the presentation of the results enable the students to understand topics in depth. In addition, their communication and team skills are promoted.

Remarks

Exercises on risk analysis and the design of safety functions are intended to deepen the knowledge acquired in the lecture and to apply newly acquired skills in a practical manner. Tasks are developed in working groups and then presented.

The presentation of solutions and the discussion of the results impart skills which are indispensable to the modern working environment of an engineer.

Recommended Literature

- Funktionale Sicherheit von Maschinen : praktische Anwendung der DIN EN ISO 13849 praktische Anwendung der DIN EN ISO 13849; Gregorius, Carsten; Berlin; Beuth Verlag; 2016; ISBN: 9783410252498
- Zertifizierung im Rahmen der CE Kennzeichnung Konformitätsbewertung und Risikobeurteilung nach der Maschinenrichtlinie 2006/42/EG und anderen europäischen Richtlinien; Schneider Andre; Berlin; VDE Verlag; 2018; ISBN 978-3-8007-4473
- Funktionale Sicherheit von Maschinen und Anlagen : Umsetzung der Europäischen Maschinenrichtlinie in der Praxis ; [Inhalt: ISO 13849-1, IEC 62061]; Gehlen; Erlangen; Publicis Publ.; 2010; ISBN: 9783895783661
- Handbook of reliability, availability, maintainability and safety in engineering design; Stapelberg; London; Springer; 2009; ISBN: 9781848001749
- Reliability engineering; Rao, Singiresu; Boston; Pearson; 2015 ; ISBN: 9780136015727
- Automotive SPICE® in der Praxis: Interpretationshilfe für Anwender und Assessoren von Markus Müller (Autor), Klaus Hörmann (Autor), Lars Dittmann (Autor), Jörg Zimmer (Autor), ISBN-13: 978-3864903267
- ISO 26262
- IEC 61508
- Norm EN ISO12100
- Norm EN ISO 13849
- Maschinenrichtlinie 2006/42/EC

MMC-13 Subject-Related Elective Course (FWP)

Module code	MMC-13
Module coordination	Prof. Dr. Peter Firsching
Course number and name	Composite Materials and Structures Computer Networking and Secure Network Management Interactive Online (CNSM) ERP Systems and Digital Transformation ROS Integrated Production Systems Product Innovation Management in Emerging Markets Python Quantum Computing Tele-Experiments with Mobile Robots Quality Management Methods & Tools Image Processing and Computer Vision Machine Vision Mathematical Methods for Simulation Embedded Linux
Lecturers	Ruben Contreras Prof. Dr. Dmitrii Dobriborsci Prof. Dr. Patrick Glauner Prof. Dr. Mathias Hartmann Prof. Dr. Maria Kufner Prof. Dr. Josef Schmid Dr. Sunil Survaiya Prof. Jürgen Wittmann Virtuelles Angebot vhb
Semester	3
Duration of the module	1 semester
Module frequency	annually
Course type	compulsory course

Level	postgraduate
Semester periods per week (SWS)	8
ECTS	5
Workload	Time of attendance: 60 hours self-study: 90 hours Total: 150 hours
Type of Examination	Examination form of the chosen module
Weighting of the grade	5 out of 90 ECTS
Language of Instruction	German, English

Module Objective

Students can choose from a range of FWP subjects as part of the compulsory elective subject module.

Students are offered, among other things, the opportunity to work on a technical project in which they are highly self-responsible and self-organized, yet work on a topic related to artificial intelligence for smart sensors and actuators under the guidance of the lecturer.

Furthermore, courses from a subject catalogue of related studies are offered at the DIT and, if applicable, the Virtual University of Bavaria (VHB), e.g.

- Advanced Modelling and Simulation (Master Mechatronic and Cyber-Physical Systems)
- Data Security and Data Protection (Master Medical Informatics)
- Collaborative Systems (Master Medical Informatics)

Further courses deepen scientific topics in the field of artificial intelligence for smart sensors and actuators.

The offer is reviewed every semester and updated if necessary.

After completing the FWP module, the students have achieved the learning goals defined in the sub-module.

In the FWP module, the following competences are to be taught:

Professional competence:

The competences result from the chosen FWP subject.

Methodological competence:

The competences result from the chosen FWP subject.

Personal competence:

The competences result from the chosen FWP subject.

Social competence:
The competences result from the chosen FWP subject.

Applicability in this and other Programs

All Master's programmes in which technical knowledge is required to solve complex problems.

Entrance Requirements

Bachelor`s degree in mechatronics or a closely related field

Learning Content

The contents result from the respective FWP subject.

Teaching Methods

The didactic methods result from the respective FWP subject.

Remarks

The FWP range of subjects includes courses with different ECTS values. Students are advised to take courses with at least 5 ECTS values.

The type of examination conducted for FWP courses is subject to the currently valid study regulations.

Recommended Literature

The literature results from the respective FWP subject.

Composite Materials and Structures

Objectives

Lightweight construction plays a special role in robotics, as moving masses are one of the safety drivers in collaborative systems. In addition, the structural mass has a significant influence on the possible payload. The precision of systems in production logistics also depends significantly on the stiffness of the structure along with position control.

Traditionally located in aerospace applications, composite materials are being used in professional autonomous systems, e.g. drones. While composite materials are already widely used in the fields of medical engineering, sports equipment and automotive, the aspect of functional integration opens up further fields of application in addition to lightweight potential in other areas of technology, such as orthotics. Active exoskeletons are one example.

Fiber-reinforced plastics have outstanding weight-related mechanical properties, namely up to a factor of 3-4 higher specific stiffness and strength compared to classic metallic materials. A fiber composite component is created with its properties in the manufacturing process. Compared to classical materials, this opens up the possibility of integral construction, i.e. of combining several components in one structure.

After attending the course "Composite Materials and Structures", the participants know the most important properties, production and applications for composite materials. This includes, in particular, the production and properties of the constituents as well as the mode of action in the composite, and the classification of different process technologies in the two production routes "liquid composite molding" and prepreg technologies.

With the acquired fundamentals regarding the mechanical behavior of layered shells (elasticity and failure), advanced aspects of load introduction as well as the principle implementation in finite element analysis, they are able to perform a preliminary design of load-bearing structures.

Fundamentals in the area of product design with special consideration of manufacturing, construction methods and quality assurance are rounded off with design guidelines for composite structures. Selected case studies are used to illustrate the approach to design, construction and dimensioning.

Entrance Requirements

Interest in high performance composite materials and applications, basic mechanics

Learning Content

1 Introduction: Applications and potential of high performance fiber reinforced materials
2 Basics composites and fiber reinforced plastics
   2.1 Levels of consideration and mode of action
   2.2 Fiber materials and their properties
   2.3 Matrix materials
   2.4 Manufacturing process technologies for composite components
   2.5 Construction methods
   2.6 Joining technology and electrochemical potential
3 Mechanical analysis of composite structures

- 3.1 Elastic behavior of composite materials
- 3.2 Failure behavior of composite materials
- 3.3 Finite element simulation of composite materials
- 3.4 Advanced topics: load introduction / joints
- 3.5 Testing

4 Aspects of the design of FV structures

- 4.1 The design and development loop
- 4.2 Product design and drawing creation
- 4.3 Damage tolerant design of composite structures

5 Case studies

Type of Examination

written ex. 90 min.

Methods

seminar-style course with exercises

Recommended Literature

Bergmann, H. W., Konstruktionsgrundlagen für Faserverbundbauteile, 1992, Springer Verlag

Schürmann, H; Konstruieren mit Faser-Kunststoff-Verbunden, Springer, 2007

Jones, Robert; Mechanics of Composite Materials, Second Edition, Taylor & Francis, 1999

Computer Networking and Secure Network Management Interactive Online (CNSM)

Objectives

The course is divided into two parts:
Part I: Fundamentals of Computer Networking
Part II: Secure Computer Network Management

Part I: Fundamentals of Computer Networking

The standard ISO/OSI computer networking model is introduced first and compared with the TCP/IP model based on RFC specifications; the roles and features of each of the layers of both models are presented.

The most important protocols and services of each layer used for networking the local and remote computers are also presented in the form of a top-down approach. All protocols are analyzed hands on using remote virtual labs and analyzer tools such as Wireshark. The roles and the main features of the network components, i.e. hub, switch, router and DNS server are addressed as well. Their operations are shown and tested using the remote virtual labs and experimental virtualized network configurations. There is also a project (programming of a simple application based on TCP and UDP sockets) which is a prerequisite for admission to the final exam.

Teaching resources offered: tutorials, lab instructions, virtualized ready set network configuration (downloadable on students' PCs), case studies, forums, exam patterns, student support materials

Part II: Secure Computer Network Management

The role and the objectives of network management (NM) for an organization are initially addressed. Various standard and private Management Information Bases (MIB) and remote MIBs are presented. The different types of network management tools, i.e. OpenNMS, NetFlow Collector, as well as the network management protocols SNMPv2/v3, NetFlow and OpenFlow network management protocols are experienced hands on based on virtualized experimental virtual networks and software tools.

Experiments are also conducted on the fundamentals of the Reconnaissance and DoS network attack types and their effects on network components and network applications to gain hand-on experience. An understanding is gained of the need for protection tools and the various types of tools. Legacy protection tools and other techniques for protecting the network components (FW, IPS, VPN) are addressed. Furthermore, secure management concepts (e.g. migration to NGFW, NGIPS, Sandbox) for the purpose of protecting against new types of attacks (e.g. ransomware, protocol anomalies) are implemented. In addition, awareness is raised of the security assurance requirements of organizations for network protection.

Teaching resources offered: tutorials, lab instructions, virtualized ready set network configuration (downloadable on students PCs), case studies, forums, exam patterns, student support material

Collaborative and cumulative project for Part II: Program and implement a secure Software Defined Network (SDN) using Snort as the intrusion attacks detector. The project is carried out in a collaborative manner by international teams of 2-3 students. The project is cumulative, i.e. each project step is based on the framework provided by the prior steps. The project is mandatory for admittance to the final exam.

Learning Content

Content:

Part I: Fundamentals of Computer Networking

- Computer Networking Terminology

- Computer Networking Architecture
- Application Layer
- Transport Layer
- Network Layer
- Multiprotocol Label Switching (MPLS)
- Data Link Layer wired networks
- Data Link Layer wireless networks
- Multimedia Technology

Part II: Secure Computer Network Management

- Surveys of Fundamentals on Computer Networks
- Network Management (NM) Architecture
- Management Information Bases (MIBs)
- NM Protocols
- Managing Network Security
- Managing Network Protection

Detailed content:

Part I: Fundamentals of Computer Networking

- Computer Networking Terminology
- Computer Networking Architecture: ISO/OSI versus TCP/IP models, role of the layers, interfaces, and protocols between layers
- Application Layer: services, application protocols (HTTP, FTP, E-Mail, DNS)
- Transport Layer: TCP protocol (sockets, analyze, error cases), UDP protocol (analyze), application programming using TCP/UDP Sockets
- Network Layer: addressing in global networks, subnetting, routing in Internet, routing algorithms, routing protocols (RIPV2 & OSPF), routing tables, ICMP protocol, protocol analyses, router operation
- Multiprotocol Label Switching (MPLS)
- Data Link Layer wired networks: CSMA/CD protocol, Ethernet versions, Ethernet analyses, VLAN principle, WAN protocols, switch operation
- Data Link Layer wireless networks: CSMA/CA protocol according to IEEE 802.11, message analyzes, access point operation
- Multimedia Technology: VoIP operation, RTP, RTCP, SIP, G.711, G.723 protocols, analyses of VoIP protocols

Part II: Secure Computer Network Management

- Surveys of Fundamentals on Computer Networks: MAC Control, TCP/IP Stack, STP protocol, VLANs, subnetting, routing algorithms, routing protocols, routing tables, QoS, CoS
- Network Management (NM) Architecture: reference model, legacy NM functionalities, proxy architecture, policy governed architecture, EVAS NM architecture (Endpoint Visualization, Access and Security), Software Defined Networks architecture (SDN), Mininet

- Management Information Bases (MIBs): standard and private MIBs (MIB II, RMON1, RMON2, ASN.1), language, Structure of Management Information (SMI), Basic Encoding Rules (BER), NM Systems (OpenNMS, NetFlow Collector)
- NM Protocols: SNMPv2, Secure SNMPv3, NetFlow, NetCONF, OpenFlow for SDNs, Case Study based on Mininet
- Managing Network Security: Confidentiality-Integrity-Availability-Model, managing Network Access Control (NAC), legacy NAC using Std. IEEE 802.1X and RADIUS; Case Study: NAC using Policy Governed Network CISCO-ISE; managing Transport Layer Secure Connections (SSL, TSL); managing Network Layer Security (IPSec and VPNs); managing Network Access Decision Control using Policy Engines
- Managing Network Protection: Type of Attacks (Reconnaissance, Denial of Service (DoS), DDoS), case studies of network attacks, managing protection methods (packet filtering, ACL, PAT/NAT, FW, VLAN, Honeypots, next generation FW (NGFW), next generation IPS (NGIPS), managing Sandboxing Protection)

Lab assignments:

1. Managing Static/RIPv2/OSPF routing
2. Monitoring/controlling CNs using SNMP v2 & v3 and MIBII technology
3. Monitoring the CN Security using OpenNMS and SNMP
4. Monitoring the CN Security using NetFlow Prot. and NetFlow Collector
5. Configuring/analyzing CN protection using FW and NAT tools
6. Programming, deploying, and analyzing various CN attacks (Reconnaissance, DoS)
7. Configuring/analyzing VPN based traffic protection using OpenVPN
8. Configuring/analyzing IPS protection using Snort
9. Configuring/analyzing network attacks using Cuckoo Sandbox
10. Monitoring/controlling SDN-based CNs using Mininet

All assignments are carried out using the virtual lab container with network components and software packages already installed. The network components are based on virtual machines and open source software tools such as Wireshark, Vyos Router supporting MIBII and SNMPv2&3, NetFlow Agents, OpenNMS, NetFlow Collector, Snort, OpenVPN, Mininet, and OpenvSwitch. All assignments are mandatory for admittance to the exam.

Type of Examination

written ex. 90 min.

Methods

Virtual seminar

Forms of interaction with the system/lecturer:
e-mail, cooperation between learner and supervisor during task processing, exercises for self-study

Forms of interaction with fellow learners:
e-mail, forum

ERP Systems and Digital Transformation

Objectives

Enterprise Resource Planning Systems (ERP systems) are part of the basic equipment of medium-sized companies and global corporations. In the operational environment they are the central application systems for controlling operational processes. As the central control unit and memory of every company, ERP systems support the operational work processes and, among other things, take over the integration task across all departments, from sales and procurement to production and accounting.
The digital transformation is changing work processes and forms of organization (see VDI 2013), which means that companies need to change their competence profiles (Gerholz 2018). Studies indicate that the ability to solve problems in the environment of operational processes and the central application systems (ERP systems), the understanding of new technologies (including the use of IoT, cloud computing, and AI) and monitoring activities (e.g., analysis of the operational databases resulting from the processes; data analytics) are important (IW 2016).
This CLASSIC vhb course addresses these needs and introduces the central, operational application systems (ERP systems). After a theoretical introduction to the topic "ERP Systems" and "Business Processes", the learning environment offers participants the opportunity to deepen their knowledge of two ERP systems (Infor VISUAL ERP and Microsoft Dynamics NAV) and to consolidate the theoretical foundations through practical experience. In the subsequent case studies **"IoT"** , **"Mobile ERP"** , and **"Data Extraction"** , participants are given the opportunity to delve into current key topics in the field of business digitization processes. As an integrating data hub, ERP systems are the central starting point for implementing these digital trends.
Internet of Things (IoT) offers the technical basis in the production environment to connect machines and material digitally with the business application systems without media discontinuity. With the IoT infrastructure, planning-relevant machine data such as machine running times, downtimes, and rejects can be automatically reported directly from the shop floor up to the strategic planning systems (ERP system). The planning process is further optimized using current and accurate data points. In the case study, Microsoft Azure and a Raspberry simulator are used as basic components to penetrate the basic architecture of IoT solutions.

Mobile ERP is the application of an ERP system on mobile devices such as tablets and mobile phones. This type of application allows data to be created and retrieved in real time regardless of the company's location. In this way, for example, customer requirements can be better met. Ultimately, this leads to an improvement in the flow of information and to an optimization of the process flows. In the case study, the participant gains experience in the application and function of mobile ERP solutions using Microsoft Dynamics NAV as an example.
Data Extraction is the basis of any digitalized system. The exchange and provision of data even across company boundaries and the evaluation of this data by data analysis tools such as Power BI, Qlik, or Tableau form the technical basis of Business Intelligence projects. The case study uses PowerBI to develop basic concepts for connectivity and data presentation.

After successful completion of the module the learner should be able to ...

- identify structural characteristics and functionalities of ERP systems and compare individual ERP systems with each other based on these,
- recognize the integration effect of ERP systems and their architecture,
- assign digital task managers to operational tasks in a targeted manner,
- describe the potential of mobile ERP applications (Mobile ERP),
- describe and implement a basic architecture for the integration of sensor data into an ERP system in the context of the Internet of Things (IoT), and
- know and apply the possibility of data extraction and evaluation in the ERP environment as the basis of Business Intelligence (BI) software.

Learning Content

- Introduction to the field of ERP systems - LEA's DREAM: From industrialization to digitalization
- ERP basic knowledge - THEORY
- ERP application - INFOR VISUAL ERP
- ERP application - MICROSOFT DYNAMICS NAV
- Case study: IOT
- Case study: MOBILE ERP
- Case Study: DATA EXTRACTION

Type of Examination

written student research project

Methods

virtual lecture

ROS

Objectives

The course offers an overview of the Robot Operating System (ROS) and its widely used tools in robotics. Through various examples, it serves as a solid foundation for students to begin working with robots. Students will gain knowledge on software development, simulation creation, sensor and actuator interfacing, and control algorithm integration.

Upon completion of this module, the student has achieved the following learning objectives:

Professional competence:

- A strong understanding of the ROS framework and its components, such as nodes, topics, messages, and services.
- Ability to create robotic applications using ROS and integrate different components, such as sensors, actuators, and controllers.
- Understanding and applying different techniques can be applied in the area of sensor, control system and many more.
- Ability to create simulations of robots and environments to test your applications.

Methodological competence:

- Application of modern software and programming techniques in robot software development.
- Implementation of robot control algorithms and integration them into ROS applications.
- Produce a ROS node: an application capable of exchanging data over the ROS middleware.
- Apply the ROS navigation stack to enable autonomous mobile robot navigation.

Personal competence:

- Application of software development concepts based on the ROS framework for research and implementation of robot motion control algorithms in complex dynamic environments.
- The students learn different concepts which can be applied to deploy robotics-related applications.

Social competence:

- Students can reflect on studying ROS can equip you with the skills and knowledge necessary to work on various robotic applications, from designing and building to programming and testing.

Entrance Requirements

Bachelor's degree in mechatronics or a closely related field

Learning Content

This course consists of a guided tutorial and exercises with increasing level of difficulty when working with an autonomous robot. You learn how to setup such a system from scratch using ROS, how to interface the individual sensors and actuators, and finally how to implement first closed loop control systems.

A strong understanding of the ROS framework and its components, such as nodes, topics, messages, and services.

- Gentle introduction to ROS
- Robot software platform
- Configuring the ROS Development Environment
- Coordinate transformation
- ROS tools: RViz, ROS GUI Development
- Creating and running Publisher and Subscriber nodes
- Communicate with ROS Topics and Services
- Navigation stack
- SLAM implementation in ROS
- MoveIt package
- Intro to ROS-Industrial package

Type of Examination

Portfolio

Methods

During the lectures, relevant theoretical knowledge will be taught. Through specific examples the students will be able to apply this knowledge to practical exercises. Here, the method of problem-based learning is centralised and is meant to promote the ability for independent acquisition of knowledge and problem-solving skills among students.

Recommended Literature

- Yoonseok Pyo, Hancheol Cho, Leon Jung, Darby Lim, ROS Robot Programming (English), 2017, Robotis
- John J. Craig, Introduction to Robotics: Mechanics and Control, 2004, Prentice Hall
- Bruno Siciliano, Oussama Khatib, Springer Handbook of Robotics, 2016
- Kevin M. Lynch and Frank C. Park, Modern Robotics: Mechanics, Planning, and Control, Cambridge University Press, 2017

Integrated Production Systems

Objectives

Participants of this course receive an overview of the tasks of a production manager in an international company:

- Motivation, philosophy, and objectives
- Methods and tools
- Experiences from industrial practice
- Overview of the current situation in terms of production systems of global acting companies

After having completed the course **'Integrated Production Systems'** students …

- understand the essential characteristics of the Lean Concept,
- know and interiorized the meaning of the existing Lean Principles,
- understand the principles and objectives of the continuous process of improvement and are able to apply the most important corresponding methods and techniques,
- understand the difference between technology- and process-orientated production,
- know the reasons for as well as possible structures and main principles of global production and corresponding supply chains,
- comprehend principles and goals of the TQM approach and are able to apply the most important corresponding methods and techniques,
- understand the Jidoka principle and resulting potential benefits,
- understand and are able to apply the TPM concept together with its eight pillars,
- comprehend and are able to quantify the material and energy flows of manufacturing companies as well as influencing factors,
- understand the meaning of information in production processes,

- know the terminology and the essentials of Lean Development and Lean Administration.

Entrance Requirements

-

Learning Content

1 Historical derivation, definition, and fundamental terms of traditional and integrated production systems (Taylorism and its realization by Henry Ford); critical analysis of the classical methods of division of responsibilities/work; Lean Production as a solution approach for the problems demonstrated
2 Description of basic pillars of integrated production systems (continuous process of improvement, Total Quality Management, value stream method, flow principle, the role of employees in the context of Lean Management)
3 Methods und tools of the continuous process of improvement: Ishikawa diagram, Pareto Analysis, A3 report, 5-W
4 Process-oriented production: differentiation to technology-orientated production, description of the key elements of flow-orientated production: Kanban, Just in Time, One Piece Flow, Heijunka
5 Global production networks in the context of Supply Chain Management: fundamentals of Supply Chain Management, supply chain structures, supply chain strategies
6 Fundamentals, elements, and tools of Total Quality Management (TQM): client orientation in the light of globalization, staff retention und assistance, risks associated with the implementation of TQM, Overall Equipment Efficiency (OEE) as a measuring instrument
7 Jidoka and Low Cost Automation (LCA): explanation of the Jidoka principle and associated tools (Poka Yoke, Andon), description of the LCA philosophy (five-levels concept), guidelines and checklists for the introduction of LCA systems
8 Total Productive Maintenance (TPM): description of seven steps for the realization of TPM, overview of TPM tools: Makigami, value stream method etc., transfer of the TPM concept into practice
9 Material and energy efficiency: measurement methods for the determination of consumptions, strategies for consumption reduction, methods for tapping the potentials of energy savings in practice, transfer of the Lean Concept to the energy value stream
10 Transfer of the Lean Concept to information provision and distribution, CAD/CAM methods, Product Lifecycle Management (PLM), Enterprise Resource Planning (ERP)

11 Lean Development: introduction to product development according to the Lean Concept, methods and tools supporting the product development process, outcome measurement instruments
12 Lean Administration: transfer of the Lean Methods to administrative and management processes, identification of administrative processes and corresponding wastage rates
13 Repetition of the contents and preparation of the written exam

Type of Examination

written ex. 90 min.

Methods

Virtual Lecture

Cooperation between learner and supervisor in task processing, exercises, exercises for self-learning, e-mail

Product Innovation Management in Emerging Markets

Objectives

The course "Product Innovation Management in Emerging Markets" is intended for future managers and entrepreneurs who want to understand the trends in the management of product innovation in an emerging markets context. The course includes a combination of online lectures, videos, keynotes, and case studies in which participants study the management of product innovation in emerging economies. Course contents include:

- An introduction to product innovation management in emerging markets
- Basic definitions and concepts of emerging markets as well as innovation
- Classification and case studies of innovations originating from emerging markets: e.g., frugal innovation, jugaad innovation, reverse innovation
- A discourse about the transformation of research and development and innovation strategies
- Current trends and outlook on the product innovation management in emerging markets

Learning Goals:

Students will ...

- ... become familiar with scientific literature about product innovation management in emerging markets,
- ... understand basic concepts of innovation and emerging markets,

- ... learn different types of innovations originating from emerging markets,
- ... apply their knowledge about innovation in emerging markets in case studies, and
- ... learn to apply the case study method as part of an interdisciplinary team (group presentation)

Important Information Regarding Exam Registration:

- FAU students: registration via MeinCampus AND the vhb portal
- Uni Bamberg students: registration via the vhb portal
- Students from other universities: registration via the vhb portal

Learning Content

Content:

1 General information
2 Introduction
3 How we define emerging markets
4 How we define innovation
5 Constraint-based innovation
6 Reverse innovation
7 Transformation of strategies
8 Future outlook
9 Group assignment

Detailed content:

1 General information - Course description - Course structure - FAQ - Course forum - Case study guidelines - Glossary

2 Introduction - Learning targets - Changing business models - Localization - Intenationalization - Summary - Further reading

3 How we define emerging markets - Learning targets - What are emerging markets - Characteristics - Comparison between developed and emerging markets - Growth drivers of emerging markets - Emerging countries - BRICS - Advantages of doing business in emerging markets - Classification of countries - Summary - Further reading

4 How we define innovation - Learning targets - Definitions - The innovation process - Emerging markets as innovation laboratories - Innovation approaches in emerging markets - Summary - Further reading

5 Constraint-based innovation - Learning targets - Introduction - What is Jugaad - From Jugaad to Frugal Innovation - What is Frugal Innovation - Case studies - Summary - Further reading

6 Reverse Innovation - Learning targets - Introduction - What is Reverse Innovation - Reverse Innovation is gaining momentum - Glocalization vs. Reverse Innovation - Reverse Innovation begins - Case studies - Summary - Further reading

7 Transformation of strategies - Learning targets - Strength and weaknesses of BRIC - Doing business in emerging markets - Major risks in emerging markets - Summary - Further reading

8 Future outlook - Learning targets - Emergence of global giants - Internationalization motives of emerging market firms - Types of firms and internationalization strategies - Upcoming trends - Summary - Further reading

9 Group assignment

Type of Examination

written ex. 90 min.

Methods

virtual lecture

Forms of interaction with the system/lecturer:
Exercises for self-study, chat

Forms of interaction with fellow learners:
Chat, forum, joint task processing

Python

Objectives

The lecture Python conveys basic and advanced knowledge about the programming language Python. Python is already widely used and spread in the industry.
After completion of this module, the student will have achieved the following learning objectives:

Professional competences:

- Programming language Python
- Typical expressions in programming

Methodical Expertise:

- Understand, analyze and alter existing programming code
- Error analysis and handling

Personal competences:

- Construct advanced Python applications
- Understand other Python-based programs and their functionality

Social competences:
- Working in a team through a project

Entrance Requirements

Bachelor's degree in mechatronics or a closely related field. In addition basic knowledge in programming and Object Oriented Programming (OOP) would be preferable.

Learning Content

- Variables
- If-Clauses
- Loops
- Functions
- Classes
- Inputs
- Exceptions
- CLI
- GUI
- Documentation
- Projects
- Decorators
- Modules
- Virtual Environments
- Testing
- Logging
- Basics of usage in Data Science

Type of Examination

written ex. 90 min.

Methods

During the lectures, relevant theoretical basic knowledge will be taught. Through specific examples the students will be able to apply this knowledge to programming exercises. Here, the method of problem-based learning is centralised and is meant to promote the ability for independent acquisition of knowledge and problem-solving skills among students.

Recommended Literature

- Romano, Fabrizio: Learning Python; Packt Publishing (2018)
- Reitz, Schlusser: The Hitchhiker's Guide to Python: Best Practices for Development; O'Reilly Media (2016)

Quantum Computing

Objectives

This class provides students with an introduction to Quantum Computing (QC), which looks promising to solve certain computational problems substantially faster than classical computers. QC began in the early 1980s and in recent years, investment into QC research has increased in both the public and private sectors. Students will acquire knowledge in QC and its applications in various domains such as machine learning and cryptography. They will also be able to elaborate it further in the future, for example in projects or further studies. Overall, QC is a cutting-edge eld, with many high-pay opportunities for graduates.

Upon completion of this module, the student has achieved the following learning objectives:

Professional competence:

- understanding of QC and its application

Methodological competence:

- elaboration of application scenarios

Personal competence:

- The students learn how to analyze and evaluate a problem and how QC can help to solve it

Social competence:

- Students are able to reflect on the requirements in the field of QC and transfer them to relevant application scenarios.

Learning Content

The following topics will be discussed in class:

- Introduction: history, comparison to traditional computing, applications, business potentials
- Foundations: complex numbers, complex vector spaces

- Systems: deterministic systems, probabilistic systems, quantum systems, assembling systems
- Quantum theory: states, superposition, observables, measuring, dynamics, assembling quantum
- systems, entanglement
- Architecture: bits and qubits, classical gates, reversible gates, quantum gates, no-cloning theorem
- Selected algorithms: Deutsch's, Deutsch-Jozsa, Simon's, Grover's, Shor's
- Theoretical computer science: limits of quantum computing, complexity classes
- Quantum computers and programming: goals and challenges, decoherence, physical realizations,
- quantum annealing, adiabatic quantum computing
- Applications: quantum machine learning, quantum cryptography, quantum information theory

Type of Examination

presentation 15 - 45 min.

Methods

This course is taught 180 minutes a week, which include lectures, laboratory sessions, seminar sessions and guest lectures. Towards the end of the term, students give a graded presentation on a selected topic related to quantum computing.

Recommended Literature

P. Glauner and P. Plugmann (Eds.), \Innovative Technologies for Market Leadership: Investing in the Future", Springer, 2020.

N. S. Yanofsky and M. A. Manucci, \Quantum Computing for Computer Scientists", Cambridge University Press, 2008.

Tele-Experiments with Mobile Robots

Objectives

The idea of this course is to use modern teleoperation and make robotics more approchable. Experiments part of this course can be performed via internet and these include experiments in robot kinematics, navigation of remote rovers, path planning and sensor data acquisition and processing. The real robot used in the experiments is a four wheeled ackermann steered real wheel driven indoor mobile robot designed and built at our department specifically for remote experiments.

Learning Content

Tele-Experiments with mobile robots" is an attempt to put basic robot theory and its implementation together to bring to students an interesting and practical course. Given that this tele-course is simultaneously used as part of regular on-site lectures, the course contents are kept up-to-date and always accessible. The experiements available here include a carefully selected mixture of real-world and simulation of robotic principles. Various topics in field robotics including kinematics, navigation principles, path planning, theoretical analysis and inverse kinematics, sensor data acquisition and processing are discussed and students are presented with challenging quizzes before beginning the experiments. Sensors are also chosen so that students get confusing results and are supposed to spend time thinking about the acquired sensor values and how to interpret those. Time delay concepts in robot teleoperation on variable bandwidth networks are also transparently presented to users as part of involuntary learning.

Contents:

1) Kinematics of a car-like mobile robot
2) Navigation control of a car-like mobile robot
3) Path planning of a car-like mobile robot
4) Modelling of the forward and inverse kinematics of differential drive robot
5) Sensor data acquisition and processing

Type of Examination

written student research project

Methods

Virtual internship

Forms of interaction with the system/lecturer:
e-mail

Forms of interaction with fellow learners:
e-mail

Quality Management Methods & Tools

Objectives

The module introduces students to the concept of quality management in engineering with the focus on statistical concepts, high end product quality, supplier quality and technical problem solving. On successful completion of this module, students should be able to understand quality management concepts, methods and tools especially in a technical and/or production environment.

Upon completion of this module, the student has achieved the following learning objectives:

Professional competence:

- understand and use statistical methods and concepts to monitor and improve production processes

- understand and use various methods to identify and eliminate technical problem root causes

- methods and concepts of quality management and quality assurance; use of AI in the field of quality

Methodological competence:

- understand and apply quality methods and tools to quality problems

- understand the overall concept of quality management ranging from statistics over organizational requirements up to quality standards and supplier/customer quality management

Personal competence:

- understand product quality as a long-term competitive advantage for companies, especially in the automotive market
- understanding and ability to use methods from different fields to improve and to monitor quality

Social competence:

- Understand quality management as a company objective to support the customer

- Ability to use various methods to achieve company quality targets

Entrance Requirements

Mathematics on a bachelor of engineering graduate level.

Learning Content

The following topics will be covered in class:

1. Statistical methods and probability
2. Capabilities
3. Statistical Process Control
4. Sub dpm Quality
5. Predictive Quality
6. Problem Solving
7. Supplier Quality Management
8. Standards & Certification

Type of Examination

written ex. 90 min.

Methods

seminar-style course with exercises

Recommended Literature

Sondermann, J. P., QM, Beuth Hochschule für Technik Berlin, Fernstudieninstitut, TFH Berlin 2006, MBA Renewable Energies

Wittmann, J., Introduction to Quality Management in the Semiconductor Industry, Vol. 1: General, ISBN-10: 1535046341; ISBN-13: 978-1535046343), CreateSpace Independent Publishing Platform, Auflage 1, Aug 2016)

Brunner F. J. Brunner, K. W. Wagner, Qualitätsmanagement, Leitfaden für Studium und Praxis, 5. Auflage, Hanser, 2011

Linß, G. Qualitätsmanagement für Ingenieure, 2. Auflage, Fachbuchverlag Leipzig, 2005

Masing T. Pfeiffer, R. Schmitt, Masing Handbuch Qualitätsmanagement, Hanser, 6. Aufl.

Wittmann, J., The Safe Launch Concept, in Quality Management in Technology, 2019, Hrsg. J. Wittmann & W. Bergholz, Kindle , Direct Publishing

Image Processing and Computer Vision

Objectives

The "Image Processing and Computer Vision" course provides students with a comprehensive understanding of the principles, algorithms, and applications of image processing and computer vision. Students will learn to manipulate, enhance, and analyze digital images and develop the skills to build computer vision systems. The course covers both theoretical foundations and practical applications, enabling students to apply image processing and computer vision techniques to real-world problems. By the end of the "Image Processing and Computer Vision" course, students will have developed a comprehensive skill set that includes advanced technology expertise, strong problem-solving abilities, and effective interpersonal and communication skills. These competences will prepare them for careers in fields such as image analysis, computer vision, machine learning, and artificial intelligence. Upon completion of this module, the student has achieved the following learning objectives:

Professional competence:

o Develop a deep understanding of image processing techniques, including filtering, enhancement, and segmentation.

o Gain skills in computer vision, covering object recognition, feature extraction, optical flow, and 3D reconstruction. o Acquire knowledge of deep learning models, especially convolutional neural networks (CNNs), for image classification, object detection, and semantic segmentation.

o Apply image processing and computer vision techniques to solve real-world problems, such as object detection, tracking, and augmented reality. o Explore emerging trends in computer vision, enabling students to stay current with the latest advancements and contribute to the field.

Methodological competence:

o Develop skills in designing experiments and evaluating the performance of image processing and computer vision algorithms. o Acquire project management skills, from conceptualization and design to implementation and testing of computer vision applications.

o Enhance problem-solving skills, particularly in diagnosing and addressing issues in image analysis and computer vision.

o Understand the importance of simulation and testing in the development and validation of computer vision systems.

Personal competence:

o Foster critical thinking and analytical skills to evaluate and improve image processing and computer vision solutions.

o Cultivate innovation and creativity in designing novel computer vision applications and addressing complex challenges.

o Improve adaptability to keep up with rapidly evolving technologies and methodologies in image processing and computer vision.

Social competence:

o Enhance the ability to work effectively in multidisciplinary teams on complex computer vision projects.

o Develop conflict resolution skills, especially in situations with differing project goals and opinions within the team.

o Improve the ability to communicate complex technical ideas to both technical and non-technical stakeholders.

Entrance Requirements

Bachelor degree in mechatronics or a closely related field.

Learning Content

Image processing and computer vision are two closely related fields in computer science and engineering that deal with the analysis, understanding, and manipulation of visual information from images and videos.

Topics:

o Introduction to Image Processing

o Image Filtering and Enhancement

o Image Segmentation and Object Recognition

o Feature Extraction and Descriptors

o Computer Vision Fundamentals o Deep Learning for Computer Vision

o Image-based rendering and augmented reality.

o Visual SLAM (Simultaneous Localization and Mapping).

Type of Examination

Portfolio

Methods

o Seminar-like teaching with joint exercises as well as presentations to deepen the knowledge achieved through application.

o i-Learn (online learning platform).

Recommended Literature

[1]. "Digital Image Processing" by Rafael C. Gonzalez and Richard E. Woods

[2]. "Computer Vision: Algorithms and Applications" by Richard Szeliski

[3]. "Deep Learning" by Ian Goodfellow, Yoshua Bengio, and Aaron Courville

[4]. "Hands-On Machine Learning with Scikit-Learn, Keras, and TensorFlow" by Aurélien Géron

[5]. "Learning OpenCV 4 Computer Vision with Python" by Joseph Howse, Prateek Joshi, and Vishwesh Ravi Shrimali

Machine Vision

Objectives

Professional competence:

XX

Methodological competence:

XX

Personal competence:

XX

Social competence:

XX

Learning Content

Type of Examination

Portfolio

Mathematical Methods for Simulation

Objectives

Modelling and simulation of physical systems play a decisive role in the digitalization of industrial processes. Beyond the use of suitable software tools, understanding the mathematics underlying these tools is a core point. In this course we will take a look behind the scenes and explore step by step the most important mathematical numerical methods. The goal is to get to know and understand the mathematical fundamentals for simulation as well as the possibilities and limitations of numerical solution methods.

Professional competence:

- Understanding the mathematical methods, which form the basis of modelling and simulation of physical systems.

- Knowledge how to choose appropriate methodes for specific application cases
- Interpretation of simulation results and critical reflexion of modelling assumptions

Methodological competence:

- Application of numerical methods for solving simulation issues.

Personal competence:

- Simulation applications can be planned and used in a technical environment. An understanding of the underlying methods is available.

Social competence:

- View to problems from the field of simulation technology from different perspectives.
- Use the skills acquired in the module in individual and group discussions as appropriate to the situation.

Entrance Requirements

Bachelor's degree in mechatronics, mechanical engineering, electrical engineering or bachelor's degree in industrial engineering, technical physics or computer engineering.

Learning Content

- Introduction to modelling and simulation
- Numeric integration and differentiation
- Numeric methods for the solution of ordinary differential equations
- Numeric methods for the solution of partial differential equations

Type of Examination

written ex. 90 min.

Methods

Seminaristic teaching with group work and joint exercises

Recommended Literature

- J.-P. Corriou: Numerical Methods and Optimization
- M. H. Holmes: Introduction to Numerical Methods in Differential Equations
- C. L. Gardner: Applied Numerical Methdods for Partial Differential Equations

Embedded Linux

Objectives

After successfully completing the module, students will have acquired the following technical, methodological, and personal skills:

- Technical skills: Students will be familiar with working with embedded Linux systems. In addition to file system structure and distribution creation, this also includes software management and driver development.
- Methodological skills: Students are able to integrate programs into a Linux environment and implement smaller embedded tasks on the software side.
- Personal skills (social skills and self-competence): Students are able to assess given problems in terms of feasibility, implementation effort and tool selection.

Entrance Requirements

Basic knowledge of programming with C/C++

Learning Content

1. Introduction to Linux
2. Shell basics
3. Bash script programming
4. Boot sequence of an embedded Linux system
5. Distribution creation
6. C++ under Linux
7. Software packages and management
8. Linux kernel modules

Type of Examination

written ex. 90 min.

Methods

seminar-style course with exercises

Recommended Literature

E-Books:

- http://openbook.rheinwerk-verlag.de/linux
- http://openbook.rheinwerk-verlag.de/linux_unix_programmierung
- http://openbook.rheinwerk-verlag.de/shell_programmierung
- http://openbook.rheinwerk-verlag.de/unix_guru/

Tutorial:

- http://www.selflinux.org/selflinux/

MMC-14 Master's Module

Module code	MMC-14
Module coordination	Prof. Dr. Peter Firsching
Course number and name	MMC3002 Master's Thesis MMC3003 Master's Seminar
Semester	3
Duration of the module	1 semester
Module frequency	
Course type	required course
Level	postgraduate
Semester periods per week (SWS)	2
ECTS	25
Workload	Time of attendance: 30 hours self-study: 720 hours Total: 750 hours
Type of Examination	colloquium, master thesis
Weighting of the grade	25 out of 90 ECTS
Language of Instruction	English

Module Objective

The Master's programme " **Mechatronic and Cyber-Physical Systems** " is completed with a Master's thesis. The students have to prove that they can work on a certain task independently and successfully within a given period of time and that they can apply scientifically founded theoretical and practical knowledge to solve a problem. After successful completion of the Master's thesis, the students are able to independently work on complex scientific/technical tasks. They solve problems with the help of digital methods and tools and master networked, cyber-physical systems.

The module content taught during the course of study is applied in the form of scientific work. The problem has to be analyzed, structured and worked on independently within a given time frame. This trains the ability to independently work on technical problems of a larger coherent topic and to prepare the results in scientific form. The aim is, among other things, to deepen and apply the ability to document the results transparently.

In addition to the Master's Thesis (20 ECTS), the Master's Seminar (5 ECTS) is also part of this module. The master's seminar consists of two parts that must be passed to successfully complete the module. To prepare for the master's thesis, participation in the seminar series "Career Start into German Technology Companies" is mandatory. The seminars / workshops are offered as block events during the first two semesters of study. The events cover a variety of topics that are of great importance for the preparation of the Master's thesis. In addition to scientific working methods, students are also introduced to application processes and the general conditions of the German labour market and its entry after graduation. The second part of the Master's seminar consists of the colloquium. After submitting the Master's thesis, it is presented in a presentation of about 15 minutes and then defended. The colloquium is assessed with 5 ECTS.

Professional competence

The students are enabled to familiarize themselves with technical tasks in depth, to analyze problems independently and to solve them.

After completing the module, students will be able to work on a problem from the extensive field of mechatroic and cyber-physical systems in a scientifically sound manner.

Methodological competence

The ability to independently work on and solve an extensive problem from the engineering sciences on a scientific basis is the overriding goal of methodological competence.

Personal competence

Independent, self-responsible and self-disciplinary scientific, methodical processing of a practice-relevant, delimitable (sub)project in a study programme-related environment as well as written, independent documentation in the form of scientific work train and required personal competences.

Social competence

The students improve their social and interface competence through intensive communication with the supervisors at DIT and in the cooperating industrial company.

Applicability in this and other Programs

The Master's programme Mechatronic and Cyber-Physical Systems enables students to work scientifically. The Master's degree entitles the holder to a subsequent doctorate.

Entrance Requirements

Admission requirements are the successfully completed case studies including the scientific elaboration of the project topics.

The registration for the Master's thesis requires that at least 30 ECTS credits have been achieved. See study and examination regulations (SPO).

Learning Content

The topic of the Master's thesis will be set by a professor of the participating universities or by a cooperating company. In addition, the students are entitled to propose their own topics. A DIT professor is responsible for supervision and content support.

The Master' thesis is included:

- Presentation of the state-of-the art in science and technology of the topic being worked on
- Description of the methodology and the course of the own theoretical and experimental procedure including concept development
- Decision making regarding the most favourable problem solution
- The integration of the own work into the work of the supervising institutes/faculties and possible industry partners.
- Report on own publications
- Report on the applications/possible applications for funding within the scope of the topic
- Creation of test setups and programs
- Execution of measurements and test runs including their evaluation
- Scientific documentation of the technical results achieved and their evaluation
- study of literature

By writing a Master' thesis, students should demonstrate their ability to apply the knowledge and skills acquired during their studies to an independent scientific thesis.

The Master' thesis is followed by a colloquium as an oral examination. The students present their Master' thesis and defend it.

Teaching Methods

Guidance to independent work according to scientific methods by the respective supervisor.

seminars, workshops,

colloquium

Remarks

The subject content of the Master' thesis can be chosen freely and individually by students. The topic must be recognised by the supervising professor. Furthermore, it is possible to work on a topic in cooperation with a company and to work on a research topic at the faculty.

Recommended Literature

Literature selected by the student for the specific subject area.

Support for scientific work:

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